

**Under Development** 

# K-Band Doppler Sensor Module for Contactless Application

RF Frequency: 24.05 to 24.25 GHz

# Model No. NJR4266A3 series

Frequency Line-up:J: 24.05 to 24.25 GHz<br/>F2: 24.15 to 24.25 GHzAntenna Type:A: TX/RX 1x1<br/>(Angle - 80°/80°, Distance - 20 to 80 cm)Interface Type:3: Digital Output / Analog Range Setting<br/>for Contactless Application

# Specifications Rev.00-01e February 12, 2021

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# 24GHz Microwave Intelligent Motion Sensor for Short Distance, Low Speed Applications with Low-profile and Low-power-consumption for Contactless Application

NJR4266 is intelligent human motion sensor module that can detect objects moving at low speed like a hand waving in a short distance range (approx. 80 cm as maximum distance) by itself and it incorporates a 24 GHz band microwave circuit, antenna, signal processing circuit, and also MCU in a  $17.2 \times 27.3 \times 5.2$  mm low profile package.

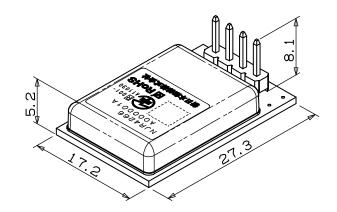
Signal processing of original technology greatly reduces false detection due to environmental noise, achieves stable detection results, and identifies directions of approach and separation. And also it has a function to reduce power consumption by sensitivity setting.

#### **Features:**

- Motion sensor using the 24GHz Microwave Doppler
- Antenna, Microwave RF circuit, IF amp, MCU and voltage regulator are integrated in a lowprofile package (17.2 x 27.3 x 5.2 mm)
- Low-power-consumption <u>1.9 mA @ 3.3 V</u>
- Sleep mode for reducing power when unnecessary
- Signal processing software for the steady sensing
  - Enhancing the signal from movement object and decreasing random noises
  - Decreasing the mutual interference between sensors
  - Detection algorisms for hand waving

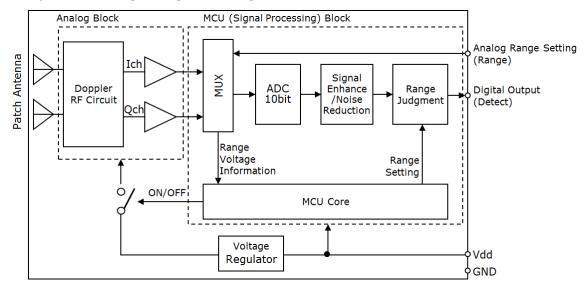
#### **Applications:**

• Contactless/touchless switch for Various equipment control



## **Functional Brock diagram:**

• Digital Output / Analog Range Setting



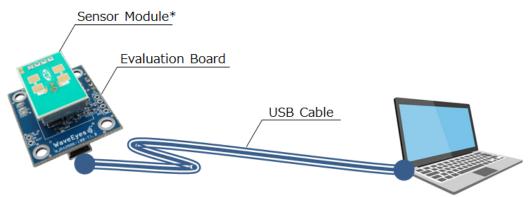
#### **Model List:**

Model No.	RF Frequency	Antenna Type	Interface Type	Region
NJR4266JA3	24.05 to 24.25 GHz (J type)	1x1 type	Digital Output / Analog Range Setting	JAPAN
NJR4266F2A3	24.15 to 24.25 GHz (F2 type)	Angle: 80º/80º Distance: 20 to 80 cm	for Contactless Application	All of EU regions / US

#### **Evaluation Kit:**

The evaluation kit is available for NJR4266 series. The contents of the evaluation kit are as follows.

- > Evaluation Kit P/N.: NJR4266K
- > Contents
  - 1. Evaluation Board (Functions are UART-to-USB convertor and analog threshold setting)
  - 2. GUI Software
  - 3. USB Cable



(\*) The sensor module itself needs to be prepared separately.

## 1. Absolute Maximum Rating

ITEM	MIN.	TYP.	MAX.	UNITS	REMARKS
Supply Voltage	0	—	6.5	V	Vdd
Source Current	—	—	100	mA	
of Detect Port					
Sink Current	—	—	100	mA	
of Detect Port					
Voltage of Range Port	-0.3	—	Vdd	V	
			+0.3		
Operating Temperature	-40	_	+85	°C	No Damage Condition. Refer to Section 9 as functional operating temperature.
Storage Temperature	-40	—	+85	°C	

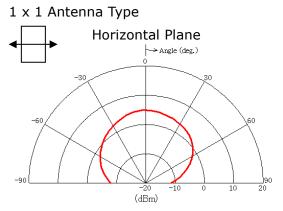
#### **2. Electrical Characteristics**

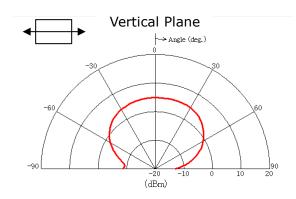
Common measure condition  $Ta = +25 \circ C$ 

ITEM	MIN.	TYP.	MAX.	UNITS	REMARKS
2.1. Power Supply					
2.1.1. Operating Voltage	3.0	3.3/5.0	5.25	V	Vdd
2.1.2. Operating Current					
1) Type of Digital Output / A	nalog Ran	ge Setting			
<ul> <li>Peak Current</li> </ul>	—	50	60	mA	
<ul> <li>Average Current</li> </ul>	—	1.9	2.3	mA	Vdd = 3.3V
	—	2.9	3.4	mA	Vdd = 5.0 V
2.2. Characteristic of Input and	Output P	orts			
Input Voltage of Range Port	-				
Range of Input Voltage	0	_	Vdd	V	Refer to item 4.3 as Analog Range Setting
Output Voltage of Detection F	Port	I		l	Analog Range Setting
Range of High Level	Vdd		Vdd	V	In case of
Range of flight Level	-0.6		vuu	v	$3.0 \le Vdd \le 4.0V$
	Vdd		Vdd	V	In case of
	-1.5		vuu	v	$4.0 < Vdd \le 5.25V$
Range of Low Level	0		0.6	V	In case of
	U		0.0	v	$3.0 \le Vdd \le 4.0V$
	0	_	1.3	V	In case of
	-		_		4.0 < Vdd ≤ 5.25V
Source Current of	_	_	10	mA	Condition to connect
Detect port					1.0kΩ pull-up resistor
Sink Current of	-	—	10	mA	Condition to connect
Detect port					1.0kΩ pull-up resistor
2.3. Sensor RF					
Conformity Standard	• MIC 1	Fechnical C	Conformity	/ (Japan):	ARIB STD-T73
		•	•	•	irective 2014/53/EU
	FCC F	Regulation	: Section	15.249 *N	lote1
Operating Frequency				<b>.</b>	
J1 type	24.05		24.25	GHz	
F2 type	24.15		24.25	GHz	
Frequency Stability (Temp.)	—	+/-0.2	—	MHz/°C	Ta = -20 to +60 °C
Output Power	1.55	3.10	4.65	mW	
E.I.R.P. (Reference)	4.8	9.6	14.3	mW	
	(6.9)	(9.8)	(11.5)	(dBm)	
2 <sup>nd</sup> Harmonics (E.I.R.P.)	—	—	-30	dBm	
2.4. Antenna					
1 x 1 antenna type					
-3dB beam width / Horizontal	—	80	—	deg.	
-3dB beam width / Vertical	—	80	—	deg.	
Side-lobe suppression / Horizontal	_	— —		dB	No Side lobe
Side-lobe suppression / hohzontai		<b></b>			

When using NJR4266 series under FCC regulation, please be sure to read and observe FCC Statement in appendix.

#### Antenna Pattern





#### 3. Sensing Specifications

3.1. Sensing Performance \*note1

Common measure condition Ta= +25 °C

ITEM	PERFORMANCE	UNITS	REMARKS
Detection Distance	20 to 80	cm	<ul> <li>♦ Front direction of the patch antenna plane.</li> <li>♦ Design value</li> <li>♦ Sensing Image is referred to figure 1.</li> </ul>

#### 3.2. Analog Voltage for Range Setting \*note1

The range setting against  $V_{dd}$  and  $V_{Range}$  is shown in figure 2.

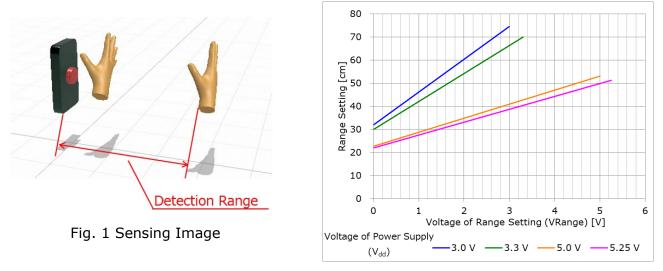


Fig. 2 Range Setting against Voltage

\*Note1) This is not the specification to guarantee the performance of this product. As for the specification of the product, the electric characteristic standard is applied. Sensing performance shown here is an example of the result of being to obtain it when this product is evaluated on the reference unit at the product development.

Actual sensing performance would be greatly different in each environment used. Please do enough confirmation in the environment actually used.

#### 4. Signal Processing of Environmental Noise Reduction

This product is embedding software for the steady sensing of moving object. It is enhance the signal from movement object of pedestrian etc. and is reduce random noise and sudden signal which caused an incorrect detection by using the signal from IQ mixer, namely **Environmental Noise Reduction**.

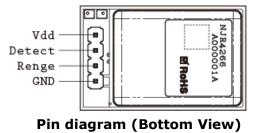
#### The following offect

The following effects are expectable. \*note1

- Reduction of false detection by random movement such as the shakes of plant by wind or the noise of rain etc.
- Reduction of the false detection by sudden movement such as the insect etc. which cross just before a sensor
- Steady detection of movement objects such as hand waving under the environment where the above-mentioned noise exists.
- Reduction of the mutual interference of sensors

### 5. Interface

5.1. Pin Assignment



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#	NAME	I/O	DESCRIPTION
1	Vdd	Ι	Power Supply: 3.0 to 5.25 V
2	Detect	0	Digital output of CMOS level for detecting hand waving. Output is changed to H level when the movements of approaching or leaving is detected. H: Detect / L: No detect Output current < 14 mA max.
3	Range	Ι	Analog range setting Refer to Item 4.3.
4	GND	-	GND Pin

Refer to item 2.2 as voltage and current of Detect/Range port Connector: Pin-header of 2.54mm pitch

# 6. Operational mode

MODE	DESCRIPTION		
Power ON / Reset	CPU Reset.		
*note1			
Initialization Mode	Initialize and wait until sensor is stabilized. (approx. 1 second )		
Detection Mode	<ul> <li>Based on the analog range setting, when the following changes occur, the voltage of the digital detect output is controlled.</li> <li>1. Detect hand waving (Voltage: H)</li> <li>3. State change from detection to no-detection (Voltage: L)</li> <li>The analog voltage of range setting is monitored in initialization mode and about every 1 second.</li> </ul>		
Wat	ch-dog-timer		

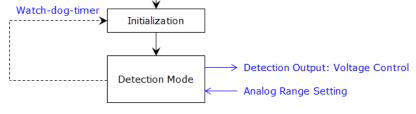
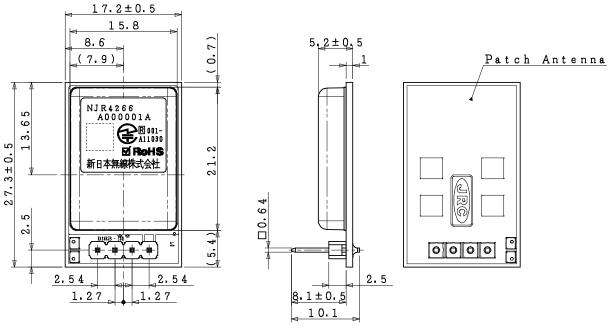


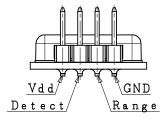
Fig.6 State Transition Diagram

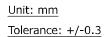
\*Note1) When the watch dog timer overflows, it is reset from any mode.

## 7. Drawing

#### 7.1. Outline

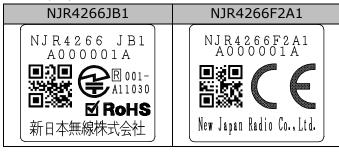






#### 7.2. Label

Example)

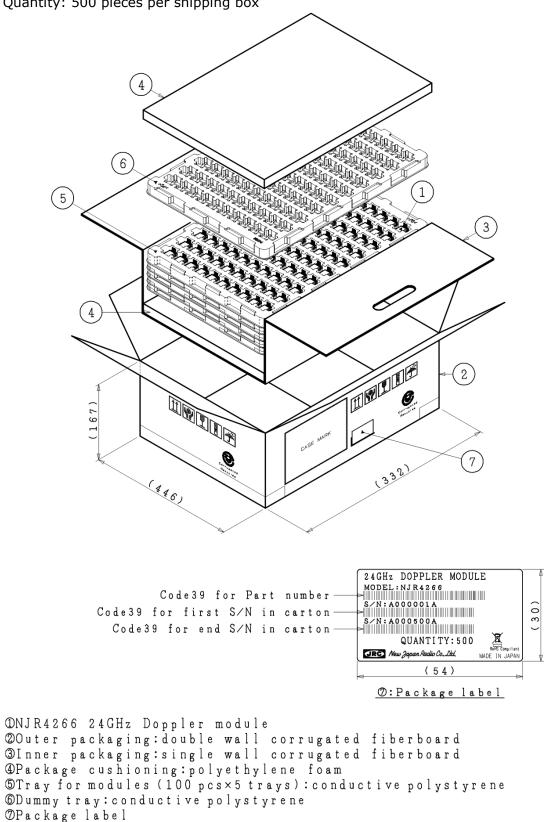


## 8. Environmental Characteristics

ITEM	SPECIFICATION
Operation Temperature	-20 to +60 °C
Storage Temperature	-40 to +85 °C
Humidity	0 to 95 % @+30 °C
Vibration	49.03 m/s <sup>2</sup> (5 G), 30 to 50 Hz, 10 minutes, XYZ direction
Shock	196.13 m/s <sup>2</sup> (20 G), Half sine, 11 msec, XYZ direction, 3 times

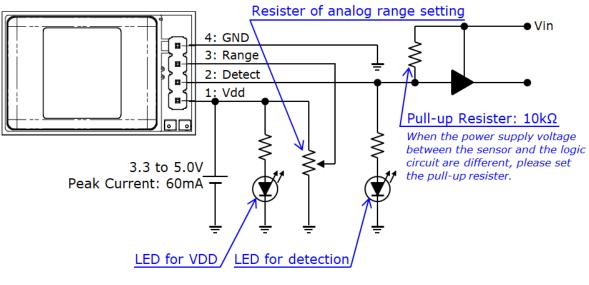
#### 9. Package

<u>Standard Package</u> Packing Quantity: 500 pieces per shipping box

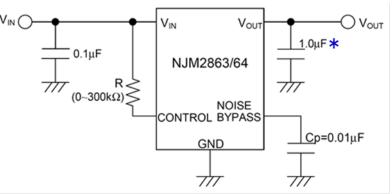


#### **10. Reference Circuit**

#### 10.1. Example



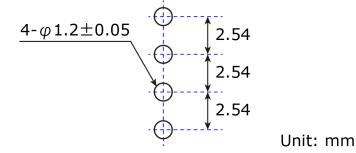
10.2. Recommendation Power Supply Circuit Recommendation linear regulator: NJM2863F33 or NJM2864F33



\* To manufacture, distribute and sell unit products using this product in the EU (European Union) accession, in order to comply with Conductive Emission (EN 55022 Class B), 22uF and more of capacitors is connected to this product's power input terminal (Pin 1: Vdd port).

#### **11. Recommendation Mounting Conditions**

11.1. Footprint dimensions



\*Note) In actual design, please optimize in accordance with the situation of your board design and soldering condition.

#### 11.2. Soldering conditions

- Soldering way: Solder iron \*Note
- Solder iron temperature: 350 °C or less
- Soldering time: in below

	#	NAME	Soldering time		
	1	Vdd	3 second or less		
-	2	UART TX	3 second or less		
		/ Detect			
	3	UART RX	3 second or less		
		/ Range			
_	4	GND	6 second or less		

\*Note) The soldering iron to be used must be grounded via a resistance of about 1 M $\Omega$ .



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